

Chapter 7

§7.6 Complex Eigenvalues

Satya Mandal, KU

Complex Eigenvalues

- ▶ We **continue** to consider homogeneous linear systems with **constant coefficients**:

$$\mathbf{x}' = \mathbf{A}\mathbf{x} \quad \mathbf{A} \text{ is an } n \times n \text{ matrix with constant entries} \quad (1)$$

- ▶ In §7.5, we considered the situation when all the eigenvalues of \mathbf{A} , were real and distinct. **In this section**, we consider when some of the eigen values are **complex**.
- ▶ As in §7.4, solutions of (1) will be denoted by

$$\mathbf{x}^{(1)}(t), \dots, \mathbf{x}^{(n)}(t).$$

Principle of superposition

- ▶ Recall the **Principle of superposition** and **the converse** (§7.4): IF $\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(n)}$ are solution of (1), then, any constant linear combination

$$\mathbf{x} = c_1 \mathbf{x}^{(1)} + \dots + c_n \mathbf{x}^{(n)} \quad (2)$$

is also a solution of the same system (1).

- ▶ The **converse** is also true, if Wronskian $W \neq 0$.
- ▶ Further, if r is an **eigenvalue** of \mathbf{A} and ξ is an **eigenvector** for r then

$$\mathbf{x} = \xi e^{rt} \quad \text{is a solution of (1)} \quad (3)$$

Complex eigenvalues and vectors

- ▶ Suppose \mathbf{A} has a complex eigenvalue $r_1 = \lambda + i\mu$ and $\xi^{(1)}$ is an eigenvector, for r_1 . That means

$$(\mathbf{A} - (\lambda + i\mu)\mathbf{I})\xi^{(1)} = \mathbf{0}. \quad (4)$$

- ▶ Apply conjugation to (4): $(\mathbf{A} - (\lambda - i\mu)\mathbf{I})\overline{\xi^{(1)}} = \mathbf{0}$. This means:
 - ▶ $r_2 = \overline{r_1} = \lambda - i\mu$ an eigenvalue of \mathbf{A} .
 - ▶ And, $\xi^{(2)} = \overline{\xi^{(1)}}$ is an eigenvector of \mathbf{A} , corresponding to r_2 .

Continued: Two conjugate complex Solutions

- ▶ Two eigen values $r_1, r_2 = \bar{r}_1$ and the corresponding eigenvalues gives two solutions of (1):

$$\mathbf{x}^{(1)} = \xi^{(1)} e^{r_1 t}, \quad \mathbf{x}^{(2)} = \xi^{(2)} e^{r_2 t} \quad (5)$$

- ▶ Write $\xi^{(1)} = \mathbf{a} + i\mathbf{b}$, where \mathbf{a}, \mathbf{b} real real vectors. Then,

$$\begin{aligned} \mathbf{x}^{(1)} &= (\mathbf{a} + i\mathbf{b})e^{(\lambda+i\mu)t} = (\mathbf{a} + i\mathbf{b})[e^{\lambda t}(\cos \mu t + i \sin \mu t)] \\ &= e^{\lambda t}(\mathbf{a} \cos \mu t - \mathbf{b} \sin \mu t) + i e^{\lambda t}(\mathbf{a} \sin \mu t + \mathbf{b} \cos \mu t) \end{aligned}$$

Continued: Two Real Solutions

- ▶ Both real and imaginary part of $\mathbf{x}^{(1)}$ are solutions of (1), as follows:

$$\begin{cases} \mathbf{u} = e^{\lambda t}(\mathbf{a} \cos \mu t - \mathbf{b} \sin \mu t) \\ \mathbf{v} = e^{\lambda t}(\mathbf{a} \sin \mu t + \mathbf{b} \cos \mu t) \end{cases} \quad (6)$$

- ▶ These real solutions \mathbf{u}, \mathbf{v} fit in very well as a **part of a fundamental set of n solutions**. There will be too many cases to make this statement precise. The textbook makes the statement in the next frame, where remaining eigenvalues are real and distinct.
- ▶ Often, we will consider systems of 2 or 3 equations. So, following statement will suffice, in most cases.

As part of Fundamental set

- ▶ Suppose $r_1 = \lambda + i\mu$, $r_2 = \lambda - i\mu$ are two conjugate eigenvalues of \mathbf{A} . As above, let $\xi^{(1)} = \mathbf{a} + i\mathbf{b}$ is an eigenvector of r_1 . Accordingly, the conjugate $\xi^{(2)} = \mathbf{a} - i\mathbf{b}$ is an eigenvector of r_2 .
- ▶ Assume r_3, \dots, r_n be the remaining eigenvalues of \mathbf{A} . Let $\xi^{(i)}$ an eigenvector of r_i , for $i = 3, \dots, n$.
- ▶ Further assume r_3, \dots, r_n are **real and distinct**.

Then, $\mathbf{u}, \mathbf{v}, \xi^{(3)}, \dots, \xi^{(n)}$ forms a fundamental set of solutions of (1). Hence, any solution \mathbf{x} has the form (2):

$$\mathbf{x} = c_1 \mathbf{u} + c_2 \mathbf{v} + c_3 \xi^{(3)} e^{r_3 t} + \dots + c_n \xi^{(n)} e^{r_n t} \quad (7)$$

Continued

- ▶ Above statement and the form of the general solution (7) hold in a much more general situation, without requiring r_3, \dots, r_n are **real and distinct**.
- ▶ **It works**, if we assume $\mathbf{u}, \mathbf{v}, \xi^{(3)}, \dots, \xi^{(n)}$ are linearly independent. Which is equivalent to

$$\begin{vmatrix} \mathbf{u} & \mathbf{v} & \xi^{(3)} & \dots & \xi^{(n)} \end{vmatrix} \neq 0$$

Sample I: Ex 5

Find the general solution (real valued) of the equation:

$$\mathbf{x}' = \begin{pmatrix} 1 & -1 \\ 5 & -3 \end{pmatrix} \mathbf{x} \quad (8)$$

- ▶ Eigenvalues of the coef. matrix \mathbf{A} , are: given by

$$\begin{vmatrix} 1-r & -1 \\ 5 & -3-r \end{vmatrix} = 0 \quad r = -1 + i, -1 - i$$

Eigenvectors

- Analytically, eigenvectors for $r = -1 + i$ is given by $(\mathbf{A} - rI)\mathbf{x} = \mathbf{0}$, which is

$$\begin{pmatrix} 1 - (-1 + i) & -1 \\ 5 & -3 - (-1 + i) \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

The second row is $2 + i$ -times the first row. It follows:

$$\begin{pmatrix} 2 - i & -1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

With $x_1 = 1$, an eigenvector of $r = -1 + i$ is

$$\xi^{(1)} = \begin{pmatrix} 1 \\ 2 - i \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix} + i \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

The solution

- ▶ So, the real and the imaginary part of $\xi^{(1)}$ are:

$$\mathbf{a} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \quad \mathbf{b} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

- ▶ With $r = -1 + i$, we have $\lambda = -1, \mu = 1$. By (6), the general solution of (8)

$$\begin{aligned} \mathbf{x} &= c_1 \mathbf{u} + c_2 \mathbf{v} = c_1 e^{-t} (\mathbf{a} \cos t - \mathbf{b} \sin t) + c_2 e^{-t} (\mathbf{a} \sin t + \mathbf{b} \cos t) \\ &= c_1 e^{-t} \left(\begin{pmatrix} 1 \\ 2 \end{pmatrix} \cos t - \begin{pmatrix} 0 \\ -1 \end{pmatrix} \sin t \right) \\ &\quad + c_2 e^{-t} \left(\begin{pmatrix} 1 \\ 2 \end{pmatrix} \sin t + \begin{pmatrix} 0 \\ -1 \end{pmatrix} \cos t \right) \end{aligned}$$

Continued

▶ $\mathbf{x} =$

$$c_1 e^{-t} \begin{pmatrix} \cos t \\ 2 \cos t + \sin t \end{pmatrix} + c_2 e^{-t} \begin{pmatrix} \sin t \\ 2 \sin t - \cos t \end{pmatrix}$$

Sample II: Ex 7

Find the general solution (real valued) of the equation:

$$\mathbf{x}' = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & -2 \\ 3 & 2 & 1 \end{pmatrix} \mathbf{x} \quad (9)$$

- Eigenvalues of the coef. matrix \mathbf{A} , are:

$$\begin{vmatrix} 1-r & 0 & 0 \\ 2 & 1-r & -2 \\ 3 & 2 & 1-r \end{vmatrix} = 0$$

$$(1-r) \begin{vmatrix} 1-r & -2 \\ 2 & 1-r \end{vmatrix} = 0$$

So, $r = 1, 1 \pm 2i$

Eigenvectors

- Eigenvectors for $r = 1$ is given by $(\mathbf{A} - rI)\mathbf{x} = \mathbf{0}$, which is

$$\begin{pmatrix} 1-1 & 0 & 0 \\ 2 & 1-1 & -2 \\ 3 & 2 & 1-1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 0 & 0 \\ 2 & 0 & -2 \\ 3 & 2 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

Use TI-84 (rref):

$$\begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 1.5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

With $x_1 = 2$, an eigenvector of $r = 1$ is: $\xi^{(1)} = \begin{pmatrix} 2 \\ -3 \\ 2 \end{pmatrix}$.

The corresponding solution $\mathbf{x}^{(1)} = \xi^{(1)} e^{rt} = \begin{pmatrix} 2 \\ -3 \\ 2 \end{pmatrix} e^t$

Eigenvectors

- Eigenvectors for $r = 1 + 2i$ is given by $(\mathbf{A} - rI)\mathbf{x} = \mathbf{0}$, which is

$$\begin{pmatrix} 1 - (1 + 2i) & 0 & 0 \\ 2 & 1 - (1 + 2i) & -2 \\ 3 & 2 & 1 - (1 + 2i) \end{pmatrix} \mathbf{x} = \mathbf{0}$$

$$\begin{pmatrix} -2i & 0 & 0 \\ 2 & -2i & -2 \\ 3 & 2 & -2i \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

So,

$$\begin{cases} -2ix_1 = 0 \\ 2x_1 - 2ix_2 - 2x_3 = 0 \\ 3x_1 + 2x_2 - 2ix_3 = 0 \end{cases} \begin{cases} x_1 = 0 \\ -2ix_2 - 2x_3 = 0 \\ 2x_2 - 2ix_3 = 0 \end{cases} \begin{cases} x_1 = 0 \\ ix_2 + x_3 = 0 \\ 0 = 0 \end{cases}$$

With $x_3 = 1$, an eigenvector of $r = 1 + 2i$ is:

$$\xi^{(2)} = \begin{pmatrix} 0 \\ i \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} i$$

Solutions corresponding to $r = 1 \pm 2i$

By (6) two real solutions, corresponding to $r = 1 \pm 2i$ are:

$$\begin{cases} \mathbf{u} = e^{\lambda t}(\mathbf{a} \cos \mu t - \mathbf{b} \sin \mu t) \\ \mathbf{v} = e^{\lambda t}(\mathbf{a} \sin \mu t + \mathbf{b} \cos \mu t) \end{cases}$$

$$\begin{cases} \mathbf{u} = e^t \left(\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \cos 2t - \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \sin 2t \right) = e^t \begin{pmatrix} 0 \\ -\sin 2t \\ \cos 2t \end{pmatrix} \\ \mathbf{v} = e^t \left(\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \sin 2t + \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \cos 2t \right) = e^t \begin{pmatrix} 0 \\ \cos 2t \\ \sin 2t \end{pmatrix} \end{cases}$$

The general solution

Combining $\mathbf{x}^{(1)}$, \mathbf{u} , \mathbf{v} , by (7), the general solution of (9) is

$$\begin{aligned}\mathbf{x} &= c_1 \mathbf{x}^{(1)} + c_2 \mathbf{u} + c_3 \mathbf{v} \\ &= c_1 \begin{pmatrix} 2 \\ -3 \\ 2 \end{pmatrix} e^t + c_2 e^t \begin{pmatrix} 0 \\ -\sin 2t \\ \cos 2t \end{pmatrix} + c_3 e^t \begin{pmatrix} 0 \\ \cos 2t \\ \sin 2t \end{pmatrix}\end{aligned}$$

Sample III: Ex 9

Solve the initial value problem:

$$\mathbf{x}' = \begin{pmatrix} 1 & -5 \\ 1 & -3 \end{pmatrix} \mathbf{x}, \quad \mathbf{x}(0) = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad (10)$$

- Eigenvalues of the coef. matrix \mathbf{A} , are: given by

$$\begin{vmatrix} 1-r & -5 \\ 1 & -3-r \end{vmatrix} = 0 \quad r = -1 + i, -1 - i$$

Eigenvectors

- Analytically, eigenvectors for $r = -1 + i$ is given by $(\mathbf{A} - rI)\mathbf{x} = \mathbf{0}$, which is

$$\begin{pmatrix} 1 - (-1 + i) & -5 \\ 1 & -3 - (-1 + i) \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 2 - i & -5 \\ 1 & -2 - i \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

The first row is $2 - i$ -times the second row. It follows:

$$\begin{pmatrix} 0 & 0 \\ 1 & -2 - i \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

- ▶ With $x_2 = 1$, an eigenvector of $r = -1 + i$ is

$$\xi^{(1)} = \begin{pmatrix} 2+i \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} + i \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

- ▶ So, the real and the imaginary part of $\xi^{(1)}$ are:

$$\mathbf{a} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}, \quad \mathbf{b} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

The solution

- ▶ With $r = -1 + i$, we have $\lambda = -1, \mu = 1$. By (6), the general solution of (8)

$$\begin{aligned}\mathbf{x} &= c_1 \mathbf{u} + c_2 \mathbf{v} = c_1 e^{-t} (\mathbf{a} \cos t - \mathbf{b} \sin t) + c_2 e^{-t} (\mathbf{a} \sin t + \mathbf{b} \cos t) \\ &= c_1 e^{-t} \left(\begin{pmatrix} 2 \\ 1 \end{pmatrix} \cos t - \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin t \right) \\ &\quad + c_2 e^{-t} \left(\begin{pmatrix} 2 \\ 1 \end{pmatrix} \sin t + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos t \right)\end{aligned}$$

Continued

► $\mathbf{x} =$

$$c_1 e^{-t} \begin{pmatrix} 2 \cos t - \sin t \\ \cos t \end{pmatrix} + c_2 e^{-t} \begin{pmatrix} 2 \sin t + \cos t \\ \sin t \end{pmatrix}$$

► Use the initial value condition:

$$\mathbf{x}(0) = c_1 \begin{pmatrix} 2 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \implies c_1 = 1, c_2 = -1$$

The Answer

- ▶ So, the answer is:

$$\mathbf{x} = e^{-t} \begin{pmatrix} \cos t - 3 \sin t \\ \cos t - \sin t \end{pmatrix}$$

§7.6 Assignments and Homework

- ▶ Read Example 1, 3 (They are **helpful**).
- ▶ **Homework**: §7.6 See Homework Site!

Ex 5

In what follows, I gave Matlab output. You can ignore the rest.

$$A = \begin{pmatrix} 1 & -1 \\ 5 & -3 \end{pmatrix}$$

$$r = -1 \pm i$$

$$V = \begin{pmatrix} 0.3651 + 0.1826i & 0.3651 - 0.1826i \\ 0.9129 & 0.9129 \end{pmatrix}$$

Ex 6

$$A = \begin{pmatrix} 1 & 2 \\ -5 & -1 \end{pmatrix}$$

$$r = \pm 3i$$

$$\begin{pmatrix} -0.1690 - 0.5071i & -0.1690 + 0.5071i \\ 0.8452 & 0.8452 \end{pmatrix}$$

Ex 7

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & -2 \\ 3 & 2 & 1 \end{pmatrix}$$

$$r = 1.0000 \pm 2.0000i, 1$$

$$V = \begin{pmatrix} 0 & 0 & 0.4851 \\ 0.7071 & 0.7071 & -0.7276 \\ 0 - 0.7071i & 0 + 0.7071i & 0.4851 \end{pmatrix}$$

Ex 8

$$A = \begin{pmatrix} -3 & 0 & 2 \\ 1 & -1 & 0 \\ -2 & -1 & 0 \end{pmatrix}$$

$$r = -1.0000 \pm 1.4142i, -2$$

$$V = \begin{pmatrix} -0.4714 + 0.3333i & -0.4714 - 0.3333i & 0.6667 \\ 0.2357 + 0.3333i & 0.2357 - 0.3333i & -0.6667 \\ -0.7071 & -0.7071 & 0.3333 \end{pmatrix}$$

Ex 9

$$A = A = \begin{pmatrix} 1 & -5 \\ 1 & -3 \end{pmatrix}$$

$$r = -1 \pm i$$

$$V = A = \begin{pmatrix} 0.9129 & 0.9129 \\ 0.3651 - 0.1826i & 0.3651 + 0.1826i \end{pmatrix}$$

Ex 10

$$A = \begin{pmatrix} -3 & 2 \\ -1 & -1 \end{pmatrix}$$

$$r = -2 \pm i$$

$$V = \begin{pmatrix} 0.8165 & 0.8165 \\ 0.4082 + 0.4082i & 0.4082 - 0.4082i \end{pmatrix}$$