

# Chapter 2: First Order ODE

## § 2.5 Existence and Uniqueness of Solutions

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# First Order DE

- ▶ We recall the general form of the First Order ODEs (FODE):

$$\frac{dy}{dt} = f(t, y) \quad (1)$$

- ▶ An ODE, with an initial value condition  $y(t_0) = y_0$  is called an **Initial Value Problem (IVP)**. So, a First Order IVP looks like:

$$\frac{dy}{dt} = f(t, y) \quad y(t_0) = y_0 \quad (2)$$

# Purpose

In this section is to consider the following two Question:

- ▶ **Question of Existence:** Given a First Oder IVP, as above (2), whether the IVP (2) has a solution  $y = \varphi(t)$ ?
- ▶ **Question of Uniqueness:** In case the IVP (2) has a solution, is the solution unique?

We dealt with such questions regarding System of Linear Equations, which was answered. Like in the case of System of Linear equations, solution to a First Oder IVP (2), **sometimes exists**, not always. But a definitive answer to these questions is **much more restrictive**. We state one such theorem, in the next frame.

# An Existence and Uniqueness Theorem

**Theorem 2.5.1:** Consider the 1<sup>st</sup>-order **Linear IVP**

$$\begin{cases} y' + p(t)y & = g(t) \\ y(t_0) & = y_0 \end{cases} \quad (3)$$

Assume  $p(t), g(t)$  are continuous on an interval  $I : \alpha < t < \beta$  and  $t_0$  is in  $I$ . Then,

- ▶ The IVP (3) has a solution  $y = \varphi(t)$ .
- ▶ The domain of  $y = \varphi(t)$  is  $I$ .
- ▶ The solution  $y = \varphi(t)$  is **unique**, on  $I$ .

# Continued

The proof of the existence of a solution would be a repetition of the steps followed in § 2.1 to solve Linear ODEs.

# The Case of Non-Linear ODEs

Now consider a nonlinear First Order IVP

$$\begin{cases} \frac{dy}{dt} &= f(t, y) \\ y(t_0) &= y_0 \end{cases}$$

- ▶ In general, existence of a solution  $y = \varphi(t)$  for such an IVP is not guaranteed, without further conditions on  $f(y, t)$ .
- ▶ Even when a solution exists, it is not guaranteed that the solution  $y = \varphi(t)$  would be unique. We would not state any other existence or uniqueness theorems.

- ▶ However, we saw that separable ODEs (§ 2.2) have solutions, whenever the respective integrals exists. Similarly, we saw Homogeneous and Bernoulli's ODEs (§ 2.4) have solutions (*under some restrictions that we ignored to state*).
- ▶ Likewise, we would see in future sections, that some other forms of ODEs have solutions.
- ▶ **Again**, things can be deceptive, as shown in the next example.

# A Deceptive Example

Consider the IVP

$$\frac{dy}{dt} = -\frac{t}{y} \quad y(0) = 0$$

This IVP seem to have a solution, while it does not.

Clarification: The ODE is separable. We have

$$\int y dy = - \int t dt + c \implies \frac{y^2}{2} = -\frac{t^2}{2} + c$$

Now,  $y(0) = 0$  implies  $c = 0$



## Continued

So, the solution to the ODE, in the implicit form is

$$\frac{y^2}{2} = -\frac{t^2}{2} \implies y^2 = -t^2$$

So, in the explicit form, the solution is

$$y = \pm\sqrt{-t^2} \quad \text{which is not a real valued function.}$$

So, the IVP does not have a (real) solution.

# Nature of Problems

We would use Theorem 2.5.1 to determine the interval, on which a Linear IVP has a solution.

# Example 1

Consider the initial value problem (IVP)

$$\begin{cases} (t+1)(t-1)(t-2)\frac{dy}{dt} + e^{t^2}y &= \sin t^2 \\ y(3) &= 1 \end{cases}$$

Use Theorem 2.5.1 to determine the interval in which this IVP has (Do not try to solve).

- ▶ Write the equation in the standard form (3):

$$\begin{cases} \frac{dy}{dt} + \frac{e^{t^2}}{(t+1)(t-1)(t-2)}y &= \frac{\sin t^2}{(t+1)(t-1)(t-2)} \\ y(3) &= 1 \end{cases}$$

# Continued

- ▶  $p(t) = \frac{e^{t^2}}{(t+1)(t-1)(t-2)}$  is not defined at  $t = -1, 1, 2$ .  
 Likewise  $g(t) = \frac{\sin t^2}{(t+1)(t-1)(t-2)}$  is not defined at  $t = -1, 1, 2$ .

Split the number line as:

$(-\infty, -1), (-1, 1), (1, 2), (2, \infty)$ .

- ▶ Both  $p(t), g(t)$  are continuous on the intervals  $(-\infty, -1), (-1, 1), (1, 2), (2, \infty)$ .
- ▶ The initial  $t$ -value  $t = 3$  is in  $(2, \infty)$
- ▶ By theorem 2.5.1 the IVP has a unique solution on the interval  $(2, \infty)$ .

# Example 2

Consider the initial value problem (IVP)

$$\begin{cases} \cos t \frac{dy}{dt} + y &= 1 + t^2 \\ y(\pi) &= 0 \end{cases}$$

Use Theorem 2.5.1 to determine the interval in which this IVP has (Do not try to solve).

- ▶ Write the equation in the standard form (3):

$$\begin{cases} \frac{dy}{dt} + \frac{1}{\cos t} y &= \frac{1+t^2}{\cos t} \\ y(\pi) &= 0 \end{cases}$$

## Continued

- ▶  $p(t) = \frac{1}{\cos t}$  and  $g(t) = \frac{1+t^2}{\cos t}$  are not defined at  $t = \dots, -\frac{\pi}{2}, \frac{\pi}{2}, \frac{3\pi}{2}, \dots$ .
- ▶ Accordingly, split the number line as:

$$\dots, \left(-\frac{\pi}{2}, \frac{\pi}{2}\right), \left(\frac{\pi}{2}, \frac{3\pi}{2}\right), \dots$$

- ▶ Both  $p(t)$  and  $g(t)$  are continuous on these intervals.
- ▶ The initial  $t$ -value  $t = \pi$  is in  $\left(\frac{\pi}{2}, \frac{3\pi}{2}\right)$ .
- ▶ By theorem 2.5.1 the IVP has a unique solution on  $\left(\frac{\pi}{2}, \frac{3\pi}{2}\right)$ .

# Nonlinear DE

- ▶ Nonlinear ODEs would not behave as nicely as in theorem 2.5.1.
- ▶ Uniqueness is not guaranteed.
- ▶ Solutions, if exist, may come out in an **implicit form**.
- ▶ Some ODEs may not have an analytic solution. In such cases, **numerical solutions** would be an option.