Matrices: §2.3 The Inverse of Matrices

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Summer 2017

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- Define inverse of a matrix.
- Point out that not every matrix A has an inverse.
- Discuss uniqueness of inverse of a matrix A.
- Discuss methods of computing inverses, particularly by row operations.
- Discuss properties of inverses.
- Apply them to solve systems of linear equations.

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Definition:

Let A be a square matrix A (of size $n \times n$).

A is said to be invertible (or nonsingular) if there exists a matrix B such that

 $AB = BA = I_n$ where I_n is the identity matrix of order n.

- Subsequently, we will see that such a B is unique (if exists), which will be called "the" inverse of A.
- Note we assumed that A is a square matrix. We will see, not all square matrices have an inverse.

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Uniqueness of Inverse

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Uniqueness of Inverse

Theorem. Suppose A is an invetible matrix. Then, its inverse is unique. This unique inverse is denoted by A^{-1} . **Proof.** Since A is invertible, it has at least one inverse. Suppose it has two inverses, B and C. By definition

$$AB = BA = I_n = AC = CA.$$
 So,

$$B = BI_n = B(AC) = (BA)C = I_nC = C.$$

So, B = C. The proof is complete.

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Example: Computing Inverse

Recall: In §2.2, HW Problem 3(b), in deed, computes the inverse of the matrix $A = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix}$, by solving

$$\left(\begin{array}{rrr}1&1\\1&2\end{array}\right)\left(\begin{array}{r}x&y\\z&w\end{array}\right)=\left(\begin{array}{r}1&0\\0&1\end{array}\right)$$

The same method is elaborated, to compute the inverse of a matrix of order 3, below.

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Inverse of a given Matrix

Let

Let
$$A = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}, \quad B = .5 \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$$
Then $AB = BA = I_2$. So, $A^{-1} = B$.

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Inverse by solving

Let
$$A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$
 and let $A^{-1} = \begin{bmatrix} a & x & u \\ b & y & v \\ c & z & w \end{bmatrix}$

Then

$$AA^{-1} = \left[egin{array}{ccc} 1 & 1 & 0 \ 1 & 0 & 1 \ 0 & 1 & 1 \end{array}
ight] \left[egin{array}{ccc} a & x & u \ b & y & v \ c & z & w \end{array}
ight] = \left[egin{array}{ccc} 1 & 0 & 0 \ 0 & 1 & 0 \ 0 & 0 & 1 \end{array}
ight]$$

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So,

$$\begin{bmatrix} a+b & x+y & u+v \\ a+c & x+z & u+w \\ b+c & y+z & v+w \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

This gives three systems of linear equations

$$\begin{cases} a+b=1\\ a+c=0\\ b+c=0 \end{cases} \begin{cases} x+y=0\\ x+z=1\\ y+z=0 \end{cases} \begin{cases} u+v=0\\ u+w=0\\ v+w=1 \end{cases}$$

We solve them as before:

$$\begin{cases} a = .5 \\ b = .5 \\ c = -.5 \end{cases} \begin{cases} x = .5 \\ y = -.5 \\ z = .5 \end{cases} \begin{cases} u = -.5 \\ v = .5 \\ w = .5 \end{cases}$$

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$$A^{-1} = \begin{bmatrix} a & x & u \\ b & y & v \\ c & z & w \end{bmatrix} = \begin{bmatrix} .5 & .5 & -.5 \\ .5 & -.5 & .5 \\ -.5 & .5 & .5 \end{bmatrix}$$

It is obvious $AA^{-1} = I_n$. We should also check $A^{-1}A = I_n$, which we skip.

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An Algorithm to find Inverse

In the above example, we solved three systems of linear equations to find the inverse. An algorithm to do the same by Gauss-Jordan Elimination is as follows:

- let A be a matrix of size $n \times n$.
- Let I be the identity matrix of order n
- Form the $n \times 2n$ matrix [A|I] by adjoining I to A.
- ► By row operations, try to reduce [A|I] to the form [I|B]. If it works, A⁻¹ = B; else, A is not invertible.
- Check (ideally) that AB = BA = I. (Subsequently, we will see that this step is not necessary.)

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Example 2.3.1

We will use the above algorithm to compute inverse of

$$A = \left[\begin{array}{rrrr} 1 & 2 & 2 \\ 3 & 7 & 9 \\ -1 & -4 & -7 \end{array} \right]$$

We adjoin the identity matrix I_3 to A, and get

Now we apply row operations.

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subtract 3 times first row from second and add first row to third:

$$\begin{bmatrix} 1 & 2 & 2 & 1 & 0 & 0 \\ 0 & 1 & 3 & -3 & 1 & 0 \\ 0 & -2 & -5 & 1 & 0 & 1 \end{bmatrix}$$

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Subtract 2 times the second row from the first and add 2 times the second row to the last:

$$\begin{bmatrix} 1 & 0 & -4 & 7 & -2 & 0 \\ 0 & 1 & 3 & -3 & 1 & 0 \\ 0 & 0 & 1 & -5 & 2 & 1 \end{bmatrix}$$

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Add 4 times the last row to the first and subtract 3 times the last row from the second:

This is in the form $[I_3|B]$. So,

$$A^{-1} = B = \left[egin{array}{cccc} -13 & 6 & 4 \ 12 & -5 & -3 \ -5 & 2 & 1 \end{array}
ight]$$

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Example 2.3.2: non- existence

Here is an example of a matrix, that does not have an inverse.

Let
$$A = \begin{bmatrix} 3 & 2 & 5 \\ 4 & 4 & 8 \\ -2 & 2 & 0 \end{bmatrix}$$

Augment the identity matrix to A: I_3 to A:

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Switch the last and the first row:

Divide the first row by -2:

$$\begin{bmatrix} 1 & -1 & 0 & 0 & 0 & -.5 \\ 4 & 4 & 8 & 0 & 1 & 0 \\ 3 & 2 & 5 & 1 & 0 & 0 \end{bmatrix}$$

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Subtract 4 times the $1^{\mathit{st}}\text{-row}$ from 2^{nd} and subtract 3 times the 1^{st} from 3^{rd} :

$$\begin{bmatrix} 1 & -1 & 0 & 0 & 0 & -.5 \\ 0 & 8 & 8 & 0 & 1 & 2 \\ 0 & 5 & 5 & 1 & 0 & 1.5 \end{bmatrix}$$

Divide second row by 8:

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Add 2^{nd} row to 1^{st} and subtract 5 times 2^{nd} row to the last:

Γ	1	0	1	.125	0	3.5
	0	1	1	0	.125	4
	0	0	0	1	.625	-18.5

The first half of this matrix does not reduce to the identity I_3 . So, A does not have an inverse.

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Determinant and Inverse of 2×2 Matrices

Let

$$A = \left(\begin{array}{cc} a & b \\ c & d \end{array}\right)$$

It follows easily:

$$\left(\begin{array}{cc} a & b \\ c & d \end{array}\right) \left(\begin{array}{cc} d & -b \\ -c & a \end{array}\right) = \left(\begin{array}{cc} ad - bc & 0 \\ 0 & ad - bc \end{array}\right)$$

• Define determinant of A as det(A) = ad - bc.

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It follows from above,

$$A^{-1} = rac{1}{ad-bc} \left(egin{array}{cc} d & -b \ -c & a \end{array}
ight) \qquad {\it if} \quad {\it ad-bc}
eq 0.$$

In next chapter is devoted to determinant of matrices of higher order. It also generalizes this formula for inverse.

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Properties of Inverses

Let A, B be two invertible matrices (of size $n \times n$), $c \neq 0$ is a scalar and k is a positive integer. Then,

•
$$(A^{-1})^{-1} = A.$$

• $(A^k)^{-1} = (A^{-1})^k$
• $(cA)^{-1} = \frac{1}{c}A^{-1}$

•
$$(A^T)^{-1} = (A^{-1})^T$$

•
$$(AB)^{-1} = B^{-1}A^{-1}$$

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Proof.

In each case, we need to verify the definition of inverse. I will only prove the last one and leave the rest as exercises. We have

$$(AB)(B^{-1}A^{-1}) = A(BB^{-1})A^{-1} = A(I)A^{-1} = AA^{-1} = I$$

and similarly $(B^{-1}A^{-1})AB = I$. So, the last statement is proved.

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Cancellation

Recall, in general, for matrices, AC = BC does not necessarily imply A = B. (Please review the example in my notes on §2.2.) But invertible matrices has the cancellation property: Let C be an invertible matrix. Then,

$$AC = BC \implies A = B.$$

$$\blacktriangleright CA = CB \implies A = B.$$

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Proof.

Suppose AC = BC. On the right side each of this equation, multiply by C^{-1} . Then we have,

$$(AC)C^{-1} = (BC)C^{-1} \Longrightarrow A(CC^{-1}) = B(CC^{-1})$$

$$\Rightarrow A(I) = B(I) \Longrightarrow A = B.$$

So, the first statement is established. Similiarly, prove the second statement.

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Theorem.

Suppose

 $A\mathbf{x} = \mathbf{b}$ Systems of Linear Equations If A is invertible, then $\mathbf{x} = A^{-1}\mathbf{b}$.

Proof.

$$A\mathbf{x} = \mathbf{b} \Rightarrow A^{-1}A\mathbf{x} = A^{-1}\mathbf{b} \Rightarrow I_n\mathbf{x} = A^{-1}\mathbf{b} \Rightarrow \mathbf{x} = A^{-1}\mathbf{b}$$

The proof is complete.

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Example 2.3.3

Compute inverse of
$$A = \begin{bmatrix} 7 & 3 & -5 \\ -2 & 3 & 2 \\ 3 & 2 & -2 \end{bmatrix}$$

Solution: Augment I_3 to A. We have

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Subtract 2 times the third row from first:

Add 2 times first row to second; then subtract 3 times first row from third:

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Add 2^{nd} row to 1^{st} ; then subtract 5 time 2^{nd} row from 3^{rd} :

Add 3^{rd} row to 1^{st} :

$$\begin{bmatrix} 1 & 0 & 0 & -10 & -4 & 21 \\ 0 & 1 & 0 & 2 & 1 & -4 \\ 0 & 0 & 1 & -13 & -5 & 27 \end{bmatrix}$$

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So,

$$A^{-1} = \left(\begin{array}{rrr} -10 & -4 & 21 \\ 2 & 1 & -4 \\ -13 & -5 & 27 \end{array}\right)$$

Exercise: Some Algebra

Exercise 2.3.4

$$A^{-1} = \begin{pmatrix} 10 & 4 & -21 \\ 2 & 1 & -4 \\ 3 & 1 & -6 \end{pmatrix} \quad B^{-1} = \begin{pmatrix} 4 & 9 & -4 \\ -2 & 4 & -1 \\ 3 & -1 & 5 \end{pmatrix}.$$

- ▶ (a) Compute (AB)⁻¹
- ▶ (b) Compute (A^T)⁻¹
- ▶ (c) Compute (2A)⁻¹

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Solution

Solution:

• (a)
$$(AB)^{-1} = B^{-1}A^{-1} =$$

$$\begin{pmatrix} 4 & 9 & -4 \\ -2 & 4 & -1 \\ 3 & -1 & 5 \end{pmatrix} \begin{pmatrix} 10 & 4 & -21 \\ 2 & 1 & -4 \\ 3 & 1 & -6 \end{pmatrix} = \begin{pmatrix} 46 & 21 & -96 \\ -15 & -5 & 32 \\ 43 & 16 & -89 \end{pmatrix}$$

Solution

Solution: (b) $(A^{T})^{-1} = (A^{-1})^{T} = \begin{pmatrix} 10 & 4 & -21 \\ 2 & 1 & -4 \\ 3 & 1 & -6 \end{pmatrix}^{T} = \begin{pmatrix} 10 & 2 & 3 \\ 4 & 1 & 1 \\ -21 & -4 & -6 \end{pmatrix}$

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Solution

Solution: (c) $(2A)^{-1} = \frac{1}{2}A^{-1} = \frac{1}{2}\begin{pmatrix} 10 & 4 & -21 \\ 2 & 1 & -4 \\ 3 & 1 & -6 \end{pmatrix} = \begin{bmatrix} 5 & 2 & -10.5 \\ 1 & .5 & -2 \\ 1.5 & .5 & -3 \end{bmatrix}$

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Example: Use inverse to Solve

Use inverse of matrices to solve

$$\begin{cases} 2x_1 & -3x_2 & -5x_3 & = 1\\ & 3x_2 & -2x_3 & = 3\\ x_1 & -2x_2 & -2x_3 & = -3 \end{cases}$$

In the matrix form:

$$\begin{pmatrix} 2 & -3 & -5 \\ 0 & 3 & -2 \\ 1 & -2 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \\ -3 \end{pmatrix}$$

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We write the system as $A\mathbf{x} = \mathbf{b}$, where

$$A = \begin{pmatrix} 2 & -3 & -5 \\ 0 & 3 & -2 \\ 1 & -2 & -2 \end{pmatrix}, \quad \mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}, \quad \mathbf{b} = \begin{pmatrix} 1 \\ 3 \\ -3 \end{pmatrix}$$

• In matrix notation solution is $\mathbf{x} = A^{-1}\mathbf{b}$, if A^{-1} exists.

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Next, we compute A^{-1} . Augment I_3 to A:

Switch first row and last row:

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Subtract 2 times 1^{st} row from 3^{rd} :

Switch 2nd and 3rd rows:

$$\left(egin{array}{ccccccc} 1 & -2 & -2 & 0 & 0 & 1 \ 0 & 1 & -1 & 1 & 0 & -2 \ 0 & 3 & -2 & 0 & 1 & 0 \end{array}
ight)$$

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Add 2 times 2^{nd} row to 1^{st} and subtract 3 times 2^{nd} from 3^{rd} :

$$\left(egin{array}{cccccc} 1 & 0 & -4 & 2 & 0 & -3 \ 0 & 1 & -1 & 1 & 0 & -2 \ 0 & 0 & 1 & -3 & 1 & 6 \end{array}
ight)$$

Add 4 times 3^{rd} row to 1^{st} and add 3^{rd} row to 2^{nd} :

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So,
$$A^{-1} = \begin{pmatrix} -10 & 4 & 21 \\ -2 & 1 & 4 \\ -3 & 1 & 6 \end{pmatrix}$$
. And, the solution :
 $\mathbf{x} = A^{-1}\mathbf{b} = \begin{pmatrix} -10 & 4 & 21 \\ -2 & 1 & 4 \\ -3 & 1 & 6 \end{pmatrix} \begin{pmatrix} 1 \\ 3 \\ -3 \end{pmatrix} = \begin{pmatrix} -6 \\ -11 \\ -18 \end{pmatrix}$

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Another Example

See the old edition of my notes for another example, of such a problem.

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